

# Lecture 17 : Frequency Response of FIR filters

how does an fir filter respond to a sinusoidal input?

- easier to interpret filter behavior + operation
- easier to compute + interpret convolution

Impulse response



$$\delta[n] = \begin{cases} 1 & \text{if } n=0 \\ 0 & \text{otherwise} \end{cases}$$

Frequency response



$$y[n] = \sum_{m=-\infty}^{\infty} h[m] x[n-m]$$

} convolution

(2)

$$= \sum_{m=-\infty}^{\infty} h[m] \cdot e^{j2\pi \hat{f}(n-m)}$$

recall  $e^{j2\pi \hat{f}(n-m)} = e^{j2\pi \hat{f}n} \cdot e^{-j2\pi \hat{f}m}$

$$= e^{j2\pi \hat{f}n} \sum_{m=-\infty}^{\infty} h[m] e^{-j2\pi \hat{f}m}$$

$x[n]$  called the "frequency response"

$$\text{Frequency Response } H(\hat{f}) = \sum_{m=-\infty}^{\infty} h[m] e^{-j2\pi \hat{f}m}$$

↓

$$\text{if } x[n] = e^{j2\pi \hat{f}n} \rightarrow [h] \rightarrow y[n] = e^{j2\pi \hat{f}n} \cdot H(\hat{f})$$

Example:  $x[n] = A \cos(2\pi \hat{f}n + \phi) \rightarrow [h] \rightarrow y[n] = ?$

by Euler

$$\rightarrow x[n] = \frac{A}{2} e^{j\phi} \underbrace{e^{j2\pi \hat{f}n}} + \frac{A}{2} e^{-j\phi} e^{-j2\pi \hat{f}n}$$

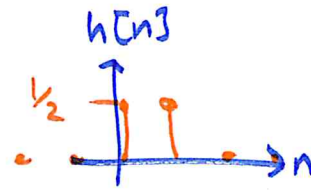
$$\Rightarrow y[n] = \frac{A}{2} e^{j\phi} e^{j2\pi \hat{f}n} H(\hat{f}) + \frac{A}{2} e^{-j\phi} e^{-j2\pi \hat{f}n} H(-\hat{f})$$

$$= A |H(\hat{f})| \cos(2\pi \hat{f}n + \phi + \angle H(\hat{f}))$$

{ the filter changes the amplitude and phase of the cosine, but not its frequency }

Ex: Moving average filter

$$h[n] = \frac{1}{2} \delta[n] \oplus \frac{1}{2} \delta[n-1]$$

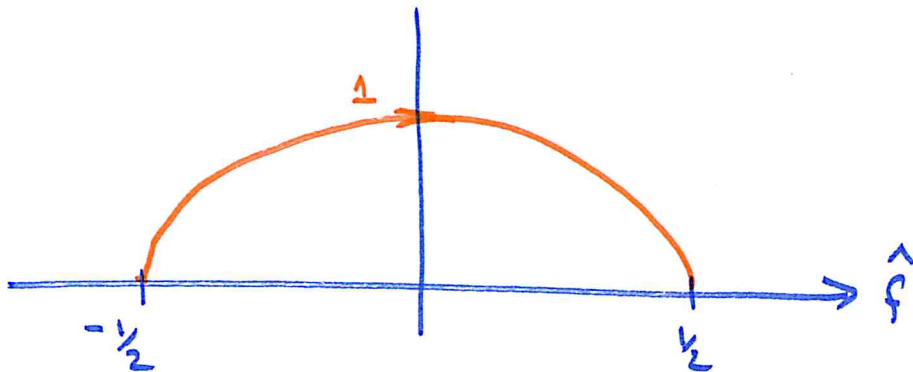


$$H(\hat{f}) = \sum_{m=-\infty}^{\infty} h[m] e^{-j2\pi \hat{f} m}$$

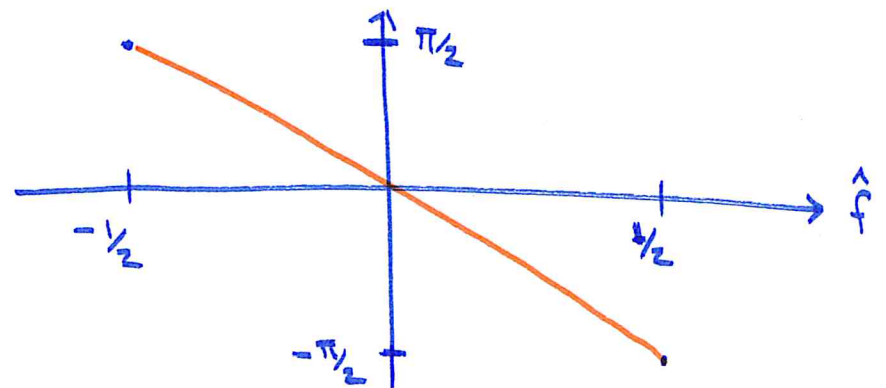
$$= \sum_{m=-\infty}^{\infty} \left( \frac{1}{2} \delta[m] + \frac{1}{2} \delta[m-1] \right) e^{-j2\pi \hat{f} m}$$

$$= \underbrace{\frac{1}{2} e^{-j2\pi \hat{f} \cdot 0}}_{= 1/2} \oplus \frac{1}{2} e^{-j2\pi \hat{f} \cdot 1} = e^{-j\pi \hat{f}} \left( \underbrace{\frac{e^{+j\pi \hat{f}}}{2} + \frac{e^{-j\pi \hat{f}}}{2}}_{= \cos(\pi \hat{f})} \right)$$

$$|H(\hat{f})| = |\cos(\pi \hat{f})|$$



$$\angle H(\hat{f}) = -\pi \hat{f}$$



- if we have input  $x[n] = \sum \cos(2\pi \hat{f}n)$

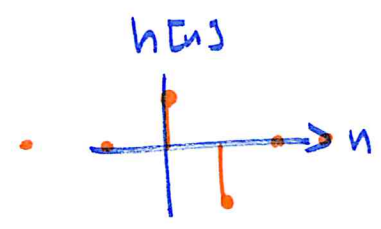
• if  $\hat{f}$  close to zero,  $|H(\hat{f})| \approx 1$   
 $\Rightarrow$  output  $\approx$  input

• if  $|\hat{f}| \approx 1/2$ ,  $|H(\hat{f})| \approx 0$   
 $\Rightarrow$  output  $\approx 0$

"low pass filter"  
b/c low frequency signals pass through (LPP)

Ex: digital differentiation

$$h[n] = \frac{s[n]}{2} - \frac{s[n-1]}{2}$$



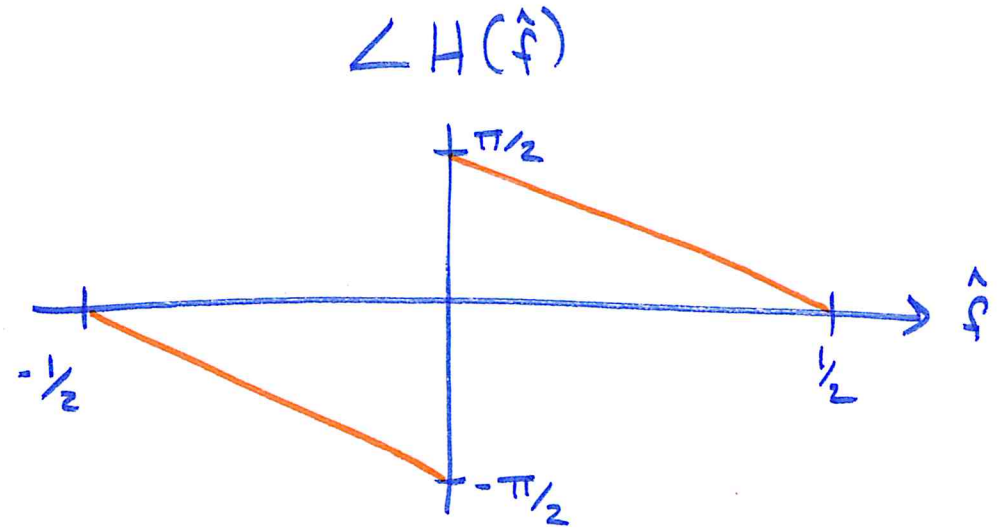
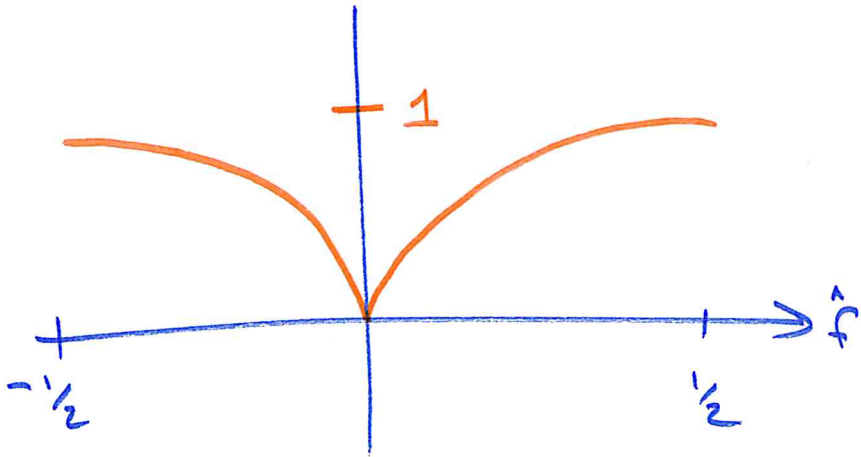
$$H(\hat{f}) = \sum_{m=-\infty}^{\infty} h[m] \cdot e^{-j2\pi \hat{f}m}$$

$$= \frac{1}{2} \ominus \frac{1}{2} e^{-j2\pi \hat{f}} = \underbrace{j}_{= e^{j\pi/2}} e^{-j\pi \hat{f}} \left( \frac{e^{+j\pi \hat{f}}}{2j} - \frac{e^{-j\pi \hat{f}}}{2j} \right) = \sin(\pi \hat{f})$$

$$H(\hat{f}) = e^{j\pi(\frac{1}{2} - \hat{f})} \sin(\pi\hat{f})$$

②

$$|H(\hat{f})| = |\sin(\pi\hat{f})|$$

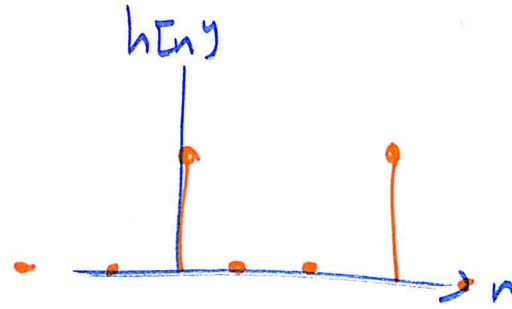


- low frequencies have small  $|H(\hat{f})| \rightarrow$  attenuated
- high frequencies are passed through

$\Rightarrow$  High-pass filter (HPF)



Ex:  $h[n] = \delta[n] + \delta[n-3]$

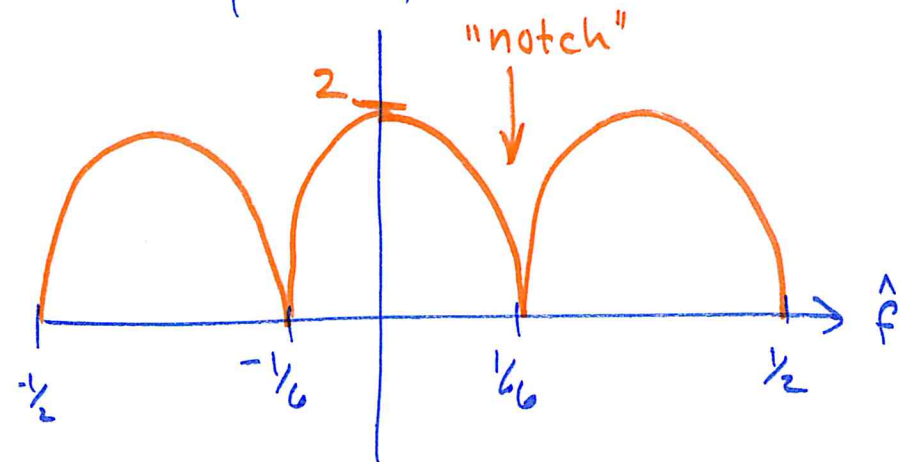


$$H(\hat{f}) = \sum_{m=-\infty}^{\infty} h[m] e^{-j2\pi \hat{f} m}$$

$$= 1 + e^{-j2\pi \hat{f} \cdot 3} = e^{-j3\pi \hat{f}} (e^{+j3\pi \hat{f}} + e^{-j3\pi \hat{f}})$$

$$= 2 e^{-j3\pi \hat{f}} \cos(3\pi \hat{f})$$

$$|H(\hat{f})| = 2 |\cos(3\pi \hat{f})|$$



"notch filter"

