

Lecture 18

Response of filters

impulse response



general input

$$x[n] \longrightarrow \boxed{h} \longrightarrow y[n] = \sum_{k=-\infty}^{\infty} h[k] x[n-k]$$

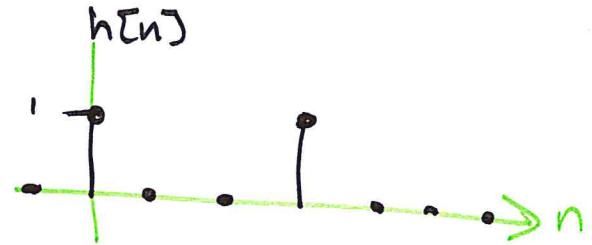
frequency response

$$e^{j2\pi \hat{f} n} \longrightarrow \boxed{h} \longrightarrow \sum_{k=-\infty}^{\infty} h[k] e^{j2\pi \hat{f} (n-k)}$$
$$= \underbrace{e^{j2\pi \hat{f} n}}_{\text{input}} \underbrace{\sum_{k=-\infty}^{\infty} h[k] e^{-j2\pi \hat{f} k}}_{\text{frequency response}}$$

$$\textcircled{*} H(\hat{f}) = \underline{\text{frequency response}}$$

$$\text{Ex: } h[n] = \delta[n] + \delta[n-3]$$

(2)



$$1+a^2 = a \left(\frac{1}{a} + a \right)$$

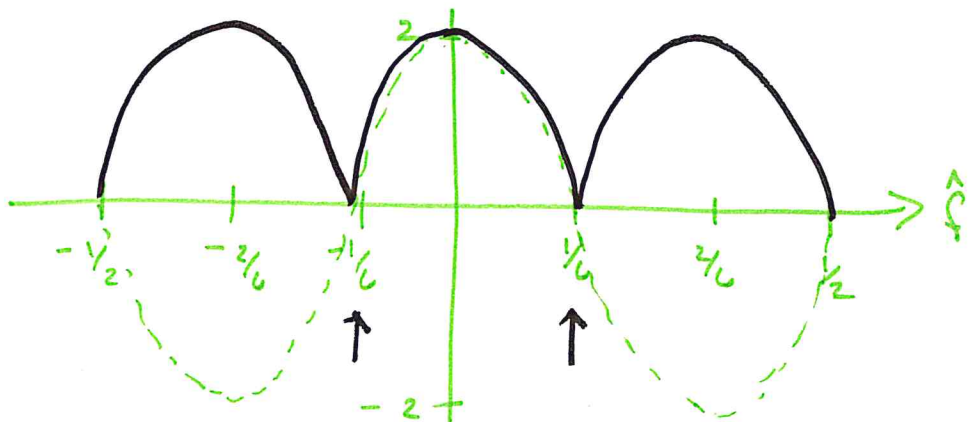
$$H(\hat{f}) = \sum_{k=-\infty}^{\infty} h[k] e^{-j2\pi \hat{f} k}$$

$$= \sum_{k=-\infty}^{\infty} (\delta[k] + \delta[k-3]) e^{-j2\pi \hat{f} k}$$

$$= 1 + \underbrace{e^{-j2\pi \hat{f} \cdot 3}}_{a^2} = \underbrace{e^{-j\pi \hat{f} \cdot 3}}_a \left(\underbrace{e^{+j\pi \hat{f} \cdot 3}}_{\frac{1}{a}} + \underbrace{e^{-j\pi \hat{f} \cdot 3}}_a \right)$$

$$= 2 e^{-j\pi \hat{f} \cdot 3} \cos(\pi \hat{f} \cdot 3)$$

$$|H(\hat{f})| = 2 |\cos(\pi \hat{f} \cdot 3)|$$



to get $\angle H(\hat{f})$

- $\hat{f} \in [-1/6, 1/6] : \cos(\pi \hat{f} \cdot 3) \geq 0$

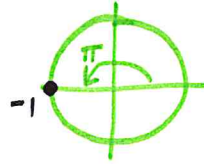
$$\Rightarrow \angle H(\hat{f}) = -\pi \hat{f} \cdot 3$$

- $\hat{f} \in (1/6, 1/2] : \cos(\pi \hat{f} \cdot 3) < 0$

$$H(\hat{f}) = \underbrace{(-2 \cos(\pi \hat{f} \cdot 3))}_{> 0} \underbrace{(-e^{-j\pi \hat{f} \cdot 3})}_{> 0}$$

recall $-1 = e^{j\pi}$

$$\begin{aligned}
 -e^{-j\pi\hat{f}3} &= e^{j\pi} e^{-j\pi\hat{f}3} \\
 &= e^{j\pi(1-\hat{f}3)}
 \end{aligned}$$



(3)

complex number

$$Ae^{j\phi}$$

where $A \geq 0$

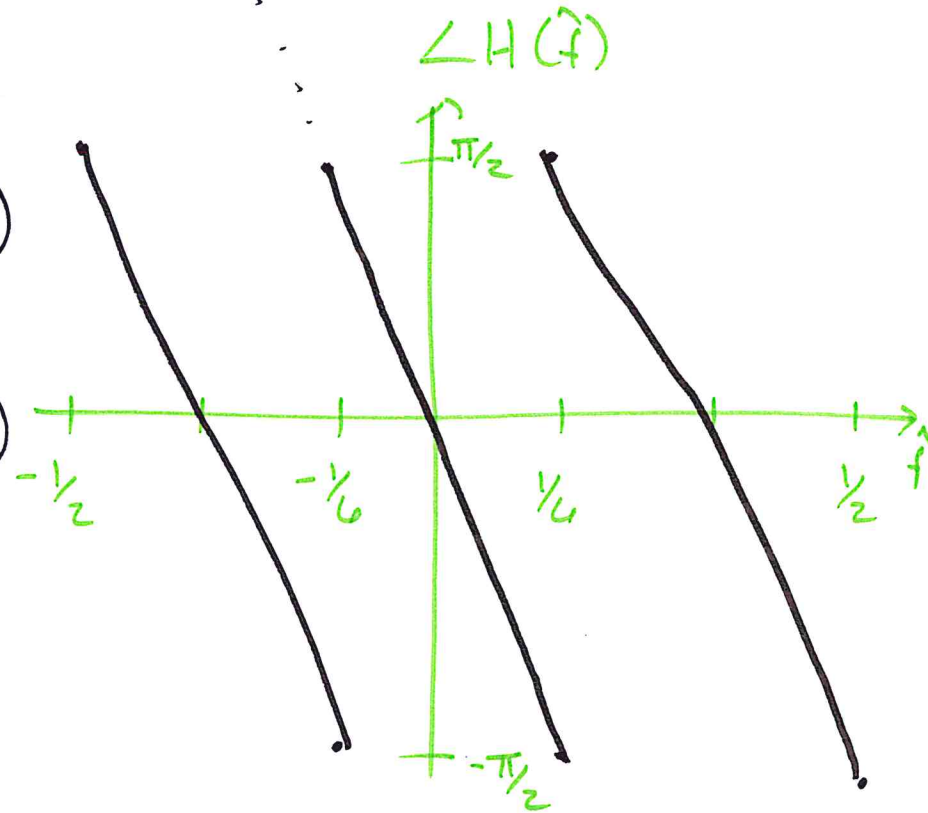
$$\Rightarrow \angle H(\hat{f}) = \underline{(1-\hat{f}3)\pi} \text{ for } \hat{f} \in (1/6, 1/2]$$

$\hat{f} \in [-1/2, -1/6) \Rightarrow \cos(\pi\hat{f}3) < 0$

$$\begin{aligned}
 H(\hat{f}) &= \underbrace{(-2\cos(\pi\hat{f}3))}_{>0} (-e^{-j\pi\hat{f}3}) \\
 &= (-2\cos(\pi\hat{f}3)) (e^{j\pi(1-\hat{f}3)})
 \end{aligned}$$

$$\Rightarrow \angle H(\hat{f}) = (1-\hat{f}3)\pi$$

$$\begin{aligned}
 @ \hat{f} = -1/2, \angle H(\hat{f}) &= (1+3/2)\pi \\
 &= \frac{5\pi}{2} = \underline{2\pi + \frac{\pi}{2}}
 \end{aligned}$$



matlab: `plot(fhat, angle(H))`

In general:

$$\text{if input is } x[n] = a_1 e^{j2\pi \hat{f}_1 n} + a_2 e^{j2\pi \hat{f}_2 n} + a_3 e^{j2\pi \hat{f}_3 n} + \dots$$

$$\text{then output is } y[n] = H(\hat{f}_1) a_1 e^{j2\pi \hat{f}_1 n} + H(\hat{f}_2) a_2 e^{j2\pi \hat{f}_2 n} + H(\hat{f}_3) a_3 e^{j2\pi \hat{f}_3 n} + \dots$$

$H(\hat{f})$ is a complex number that reflects how a filter changes the magnitude and phase of an input sinusoid of frequency \hat{f} . $H(\hat{f}) = |H(\hat{f})| e^{j\angle H(\hat{f})}$

From frequency response, we can impulse response:

$$H(\hat{f}) = \sum_{k=-\infty}^{\infty} h[k] e^{-j2\pi \hat{f} k}$$

$$\text{so if } H(\hat{f}) = \underline{b_0} + \underline{b_1} e^{-j2\pi \hat{f} \cdot 1} + \underline{b_2} e^{-j2\pi \hat{f} \cdot 2} + \underline{b_3} e^{-j2\pi \hat{f} \cdot 3} + \dots$$

$$\text{then } \underline{h[n]} = \underline{b_n}$$

What if input $x[n] = 1 + \cos(2\pi \frac{1}{6} n)$?

$$= 1 \cdot e^{j2\pi \cdot 0 \cdot n} + \frac{1}{2} e^{j2\pi \frac{1}{6} n} + \frac{1}{2} e^{-j2\pi \frac{1}{6} n}$$

$$y[n] = 1 \cdot e^{j2\pi \cdot 0 \cdot n} H(\hat{f}=0) + \frac{1}{2} e^{j2\pi \frac{1}{6} n} H(\hat{f}=\frac{1}{6}) + \frac{1}{2} e^{-j2\pi \frac{1}{6} n} H(\hat{f}=-\frac{1}{6})$$

$$H(\hat{f}=0) = 2$$

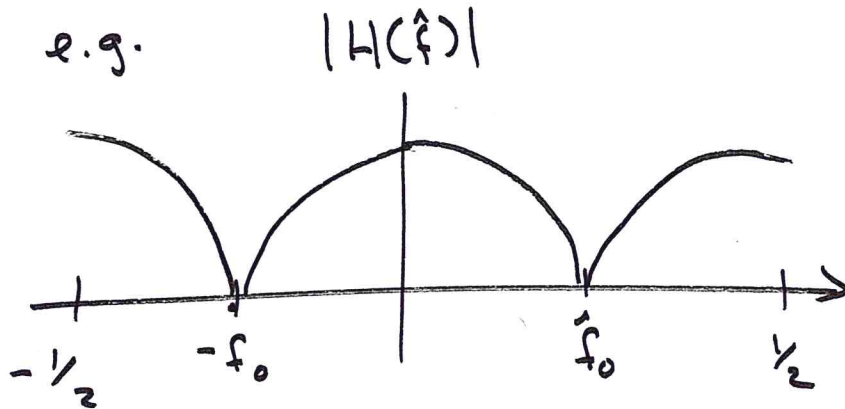
$$H(\hat{f}=\frac{1}{6}) = 0 \Rightarrow y[n] = 2$$

$$H(\hat{f}=-\frac{1}{6}) = 0$$

Filter design

(5)

Let's design a filter to remove a particular frequency \hat{f}_0



One approach: set $H(\hat{f}) = (e^{-j2\pi\hat{f}} - e^{-j2\pi\hat{f}_0})(e^{-j2\pi\hat{f}} - e^{+j2\pi\hat{f}_0})$

$$= e^{-j4\pi\hat{f}} - e^{-j2\pi(\hat{f}-\hat{f}_0)} - e^{-j2\pi(\hat{f}+\hat{f}_0)} + 1$$

$$= e^{-j4\pi\hat{f}} - e^{-j2\pi\hat{f}} \left(\frac{e^{j2\pi\hat{f}_0} + e^{-j2\pi\hat{f}_0}}{2} \right) \cdot 2 + 1$$

$$= \underbrace{e^{-j4\pi\hat{f}}}_{e^{-j2\pi\hat{f}k} \quad \omega/k=2} - \underbrace{e^{-j2\pi\hat{f}}}_{e^{-j2\pi\hat{f}k} \quad \omega/k=1} \cdot \cos(2\pi\hat{f}_0) \cdot 2 + 1 \quad \underbrace{1}_{e^{-j2\pi\hat{f}k} \quad \omega/k=0}$$

$$H(\hat{f}) = \underbrace{1}_{h[0]} \cdot e^{-j2\pi\hat{f}\cdot 0} - \underbrace{2\cos(2\pi\hat{f}_0)}_{h[1]} e^{-j2\pi\hat{f}\cdot 1} + \underbrace{1}_{h[2]} \cdot e^{-j2\pi\hat{f}\cdot 2} \quad (6)$$

$$h[n] = \delta[n] - 2\cos(2\pi\hat{f}_0) \delta[n-1] + \delta[n-2]$$

Ex: $h_1[n] = \delta[n] - g\delta[n-1]$

$$H_1(\hat{f}) = \sum_{k=-\infty}^{\infty} h[k] e^{-j2\pi\hat{f}k} = \sum_{k=-\infty}^{\infty} (\delta[k] - g\delta[k-1]) e^{-j2\pi\hat{f}k}$$

$$= 1 - g e^{-j2\pi\hat{f}}$$

$$\text{Ex : } h_2[n] = \sum_{l=0}^M r^l \delta[n-l]$$

$$H_2(\hat{f}) = \sum_{k=-\infty}^{\infty} \left(\sum_{l=0}^M r^l \delta[k-l] \right) e^{-j2\pi k \hat{f}}$$

$$= \sum_{l=0}^M r^l \left(\sum_{k=-\infty}^{\infty} \delta[k-l] e^{-j2\pi k \hat{f}} \right)$$

$$= \sum_{l=0}^M r^l e^{-j2\pi l \hat{f}} = \sum_{l=0}^M \left(r e^{-j2\pi \hat{f}} \right)^l$$

$$= \frac{1 - \left(r e^{-j2\pi \hat{f}} \right)^{M+1}}{1 - r e^{-j2\pi \hat{f}}}$$

⑦