Lecture 4: Least Squares and Optimization

Example

Least Squares & Classification

Setup: n training samples, (x, y,) ERP x {-1, +1} for i=1, ..., n

Let
$$X = \begin{bmatrix} -\underline{x}, \\ -\underline{x}, \\ \vdots \\ -\underline{x}, \end{bmatrix}$$
, $Y = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$

Assume n>p, X is rank-p. Then

Y = X û ER (ie not +1 or -1 labels)

compute $\hat{v} = argmin \|y - X_w\|_2^2$,

Classification rule: predict +1 if y >0 and + if y, <0 ⇒ ý; - sign (ÿi) ý - sign (ý)

for a new sample × new ETR, want to predict new, unknown label ynew. Ynew = < xnew, w > ER ynew = sign (Ynw)

alternatively we might be tempted to consider w = argmin | y - sign(Xw)|2

but this is very hard to solve

$$\hat{\underline{w}} = \text{"argument } \underline{w} \text{ dhat minimizes"} \sum_{i=1}^{n} r_i^2(\underline{w})$$

$$= \underset{\underline{w}}{\operatorname{argmin}} \sum_{i=1}^{n} r_{i}^{2} (\underline{w})$$

= argmin
$$\|\underline{\Gamma}\|_{2}^{2}$$

$$= \underset{y}{\operatorname{argmin}} \sum_{j=1}^{n} \left(y_{j} - \sum_{j=1}^{p} W_{j} \times y_{j} \right)^{2} = \underset{\underline{W}}{\operatorname{argmin}} \left\| y - X \underline{w} \right\|_{2}^{2}$$

$$= \underset{\underline{w}}{\operatorname{argmin}} \quad \left\| \underline{y} - \underline{X} \underline{w} \right\|_{2}^{2}$$

2-norm or Euclidean norm:
$$\left\| \underline{a} \right\|_{2} := \left(\sum_{i=1}^{n} a_{i}^{2} \right)^{2}$$

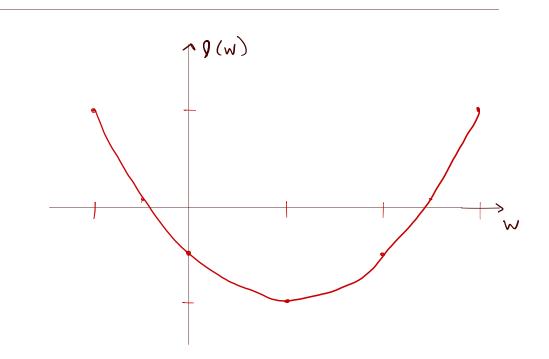
$$= \underset{\underline{w}}{\operatorname{argmin}} \quad \underline{y}^{\mathsf{T}}\underline{y} - \underline{y}^{\mathsf{T}}\underline{X} \,\underline{w} - \underline{w}^{\mathsf{T}}\underline{X}^{\mathsf{T}}\underline{y} + \underline{w}^{\mathsf{T}}\underline{X}^{\mathsf{T}}\underline{X}\,\underline{w}$$

Warmup.

$$\int (w) = \frac{1}{2} \omega^2 - w - \frac{1}{2}$$

$$\hat{w} = \underset{w}{\text{argmin}} \quad \mathcal{V}(w)$$

$$\frac{d9}{dw} = 2 \cdot \frac{1}{2} w - 1 = 0 \implies \hat{w} = 1$$



Positive definite matrices

this does not

elements of

mean all

From the geometric perspective, we saw that it was important for finding a unique least squares solution w that X'X be invertible.

Is this important in the optimization Setting as well? YES!

The following two - things are equivalent for XER NXP with n = p, rank(X) = p (X has p linearly independent columns)

- (2) X'X is positive definite

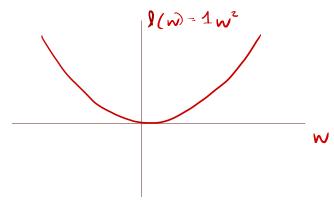
A matrix Q is positive definite (p.d.) if $\underline{w}^{T} \bigcirc \underline{w} > 0$ for all $\underline{w} \neq 0$ Shorthand Q>0 A matrix Q is positive semi-definite (p.s.d.) if $\underline{w}^{T} \bigcirc \underline{w} \geq 0$ for all $\underline{w} \neq 0$ are positive Shorthand Q >0 or non-negative!



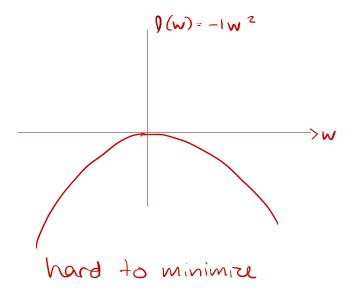
 \mathcal{E}_{x} : $W \in \mathbb{R}$, $Q \in \mathbb{R} \implies \sqrt[4]{Q} W = Q_{W}^{2} > 0$ is Q > 0

imagine trying to minimize I(w) = Qw2

$$\int (w) = Q w^2$$

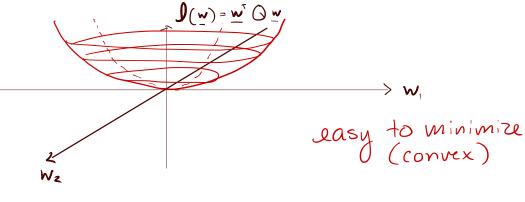




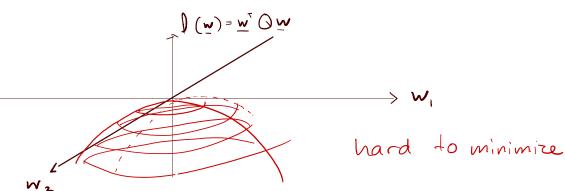


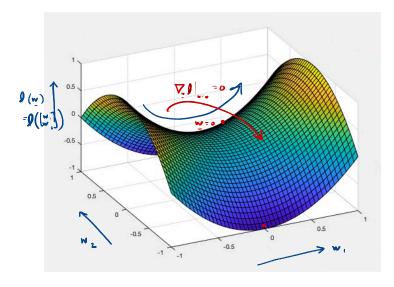
(convex) Zx WeR2, QER2x2

$$Q > 0$$
 b/c $w^T Q w = w_1^2 + w_2^2 > 0$



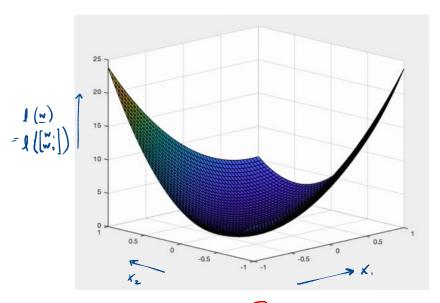
$$Q = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} \implies$$





this an example of a "saddle point"

Q is <u>NOT</u> positive definite



$$Q = \begin{bmatrix} 5 & -5 \\ -5 & 1 \end{bmatrix}$$
Recall Q is positive if w'Qw > 0 for all $w \neq 0$

$$Q(w) = w^{T}Qw$$

$$Q(w) > 0 \text{ for } w \neq 0$$

Properties of Positive Definite Matrices

- Dif P>0 and Q>0, then P+Q>0
- $\overline{M}_{\perp} \overline{DM} > 0 \quad \overline{M}_{\perp} \overline{GM} > 0 \Rightarrow \overline{M}_{\perp} (\overline{D}_{\perp} \overline{G}) = \overline{X}_{\perp} \overline{D} \times + \overline{X}_{\perp} \overline{G} \times > 0$
- 2) if Q > 0 and a > 0, then aQ > 0 $\underline{w}^{T} Q \underline{w} > 0 \implies \underline{w}^{T} (aQ) \underline{w} = a \underline{w}^{T} Q \underline{w} > 0$
- 3) for any A, $A^TA \geq 0$ and $AA^T \geq 0$
 - if the columns of A are linearly independent, then ATA >0

Note $\underline{w}^T \underline{w} \ge 0$ always, and $\underline{w}^T \underline{w} = 0$ only if $\underline{w} = 0$.

Let $\tilde{\underline{w}} := A\underline{w}$

 $\underline{w}^T A^T A \underline{w} = \underline{w}^T \underline{w}^T \ge 0$ Now $\underline{w}^T \underline{w} = 0$ only if $\underline{w}^T = A \underline{w} = 0$. $A \underline{w} = 0$ if either @ $\underline{w} = 0$ or \underline{b} columns of A are linearly dependent.

- 4) if $Q \succ 0$, then Q^{-1} exists (consider special case where Q is diagonal $Q = \begin{bmatrix} \vartheta & 0 \\ 0 & q \end{bmatrix}$ $\Rightarrow 0 \succ 0 \Leftrightarrow \text{all } g_1 > 0$
- 5) Q>P means Q-P>0

If Q = X X, is Q positive definite?

For Q to be PD, need w Ow >0 for all w to

 $N \circ W = W \times X \times W = W \times W \times W = W \times W \times W = X \times W =$

For Ω to be positive definite (not positive semi definite, where $\underline{w}^*\Omega \underline{w} = 0$) we need to remsure $\widetilde{w}^*\widetilde{w} > 0$

Now $\tilde{w}'\tilde{w} = 0$ only if $\tilde{w} = 0$ (because $\tilde{w}'\tilde{w} = \tilde{w}_1^2 + \tilde{w}_2^2 + \cdots = \tilde{w}_p^2$)

w=0 if Xw=0. Can Xw=0 for some w≠0?

Recall Xw = weighted sum of columns of X. Ie Xw w, X, +w, X, + v + W, Xp

Recall defn of linear independer: The columns of X are L.I. if no weighted sum = 0 (unless all weights =0)

If cols. of X are LI, then $X_{\underline{W}} \neq 0$ unless $\underline{W} = 0$ $\Rightarrow W \times X \times V > 0 \Rightarrow X \times V = 0$ is pos definite

$$\underline{\hat{w}} = \underset{\underline{w}}{\operatorname{argmin}} \mathbf{I}(\underline{w}) \quad \text{where } \mathbf{I}(\underline{w}) = \underline{y}^{\mathsf{T}} \underline{y} - \underline{y}^{\mathsf{T}} \underline{X} \underline{w} - \underline{w}^{\mathsf{T}} \underline{X}^{\mathsf{T}} \underline{y} + \underline{w}^{\mathsf{T}} \underline{X}^{\mathsf{T}} \underline{X} \underline{w}$$

I(w) maps were to R

Assume l(w) is convex (more on this later): When w is a scalar, we set derivative $\frac{dl}{dw}$ to zero and solve for w.

When w is a vector, we set gradient of to zero and solve for w

 $\mathcal{E}_{x} \quad \mathcal{Q}(\underline{w}) = \underline{w}^{T} \underline{c} = c_{1}w_{1} + c_{2}w_{2} + \cdots + c_{p}w_{p}$ $\nabla_{w} = C_{1}$ $C_{2} = \underline{c}$ where 1

 $\mathcal{E}_{x} \quad \mathcal{Q}(\underline{w}) = \|\underline{w}\|^{2} = \underline{w}^{T} \underline{w} = \underline{w}_{1}^{2} + \underline{w}_{2}^{2} + \underline{w}_{1}^{2} + \underline{w}_{2}^{2}$ $\nabla_{w} \mathbf{1} = \begin{bmatrix} 2 \underline{w} \\ 2 \underline{w}_{2} \end{bmatrix} = 2 \underline{w}$ $2 \underline{w}_{2}$ $2 \underline{w}_{2}$

$$\mathcal{E} \times \mathcal{A}(\underline{w}) = \underline{w}^{T} Q \underline{w} = \sum_{i=1}^{p} \sum_{j=1}^{p} W_{i} Q_{ij} w_{j}$$

$$d(\underline{w}_{i}Q_{ij}w_{i}) = \begin{cases} Q_{kk}W_{k} & \text{if } k=i-j \\ Q_{kj}W_{j} & \text{if } i=k\pm j \\ Q_{ik}W_{i} & \text{if } j=k\pm i \end{cases}$$

$$\frac{d}{dw_{k}} = \sum_{i=1}^{p} \sum_{j=1}^{p} \underline{d(w_{i}Q_{ij}W_{i})}$$

$$\Rightarrow \nabla_{\underline{w}} P = Q_{\underline{w}} + Q_{\underline{w}}^{T}.$$
if Q is symmetric (ie. $Q = Q_{\underline{v}}^{T}$), Alun
$$\nabla_{\underline{w}} P_{\underline{w}} Q_{\underline{w}} = 2Q_{\underline{w}}$$
"Rule 2"

Ex. least squares:
$$l(\underline{w}) = \underline{y}^{T}\underline{y} - \underline{\partial}\underline{w}^{T}\underline{X}^{T}\underline{y} + \underline{w}^{T}\underline{X}^{T}\underline{X}\underline{w}$$

$$l(\underline{w}) = \sum_{i=1}^{n} (\underline{y}_{i} - \underline{x}_{i}^{T}\underline{w})^{2} = \|\underline{y} - \underline{X}\underline{w}\|_{2}^{2}$$

$$= (\underline{y} - \underline{X}\underline{w})^{T}(\underline{y} - \underline{X}\underline{w})$$

$$= (\underline{y} - \underline{X}\underline{w})^{T}(\underline{y} - \underline{X}\underline{w})$$

$$= \underline{y}^{T}\underline{y} - \underline{y}^{T}\underline{X}\underline{w} - \underline{w}^{T}\underline{X}^{T}\underline{y} + \underline{w}^{T}\underline{X}^{T}\underline{X}\underline{w}$$

$$= \underline{y}^{T}\underline{y} - \underline{\partial}\underline{w}^{T}\underline{X}^{T}\underline{y} + \underline{w}^{T}\underline{X}^{T}\underline{X}\underline{w} \longrightarrow \underline{X}^{T}\underline{X}$$

$$= \underline{y}^{T}\underline{y} + \underline{\partial}\underline{x}^{T}\underline{X}^{T}\underline{y} + \underline{\partial}\underline{X}^{T}\underline{X}\underline{w} \longrightarrow \underline{X}^{T}\underline{X}$$

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$$\nabla_{\underline{w}} Q = O - 2 \times^{T} y + 2 \times^{T} \chi_{\underline{w}}$$

If $Q = X^TX > 0$, then we can compute gradient and set it to zero because f is convex

$$\nabla_{\underline{w}} = 0$$

$$\Rightarrow X^{T} X \hat{\underline{w}} = X^{T} Y$$

$$\Rightarrow \hat{\underline{w}} = (X^{T} X)^{T} X^{T} Y \quad (\text{what we got from geometric perspective})$$

So far, we're assumed X cR ncp has n≥p and p cols of X are LI.

- · Colums of X are LI -> Q = XTX > O (ie XTX is positive definite)
- · X X is pos definite > least square loss yy-2w Xy + W X Xw is convex
- if $X^TX > 0$, then X^TX has inverse
- X^TX has inverse \Rightarrow $\hat{w} = (X^TX)^TX^Ty$ exists and is unique